### eposcorr

February 1, 2016

#### Abstract

Adds corrected source positions to the EPIC source list by cross-correlation with optical source catalogue.

## 1 Instruments/Modes

	Instrument	Mode	
EPIC		Imaging	

## 2 Use

pipeline processing	yes
interactive analysis	no

# 3 Description

The **eposcorr** task reads the X-ray source positions from an input fits-file and correlates those with the positions from an optical source catalogue. The correlation algorithm checks whether there are offsets in RA and DEC which optimize the correlation. To do this a particular statistic is used and its value calculated for a grid of 30x30 offset values with a resolution, which can be controlled by input parameters. If demanded a similar grid search is done for roll angle errors. In that case, first a 3dimensional grid search will be done and then several iterations with alternating RA/DEC offsets and rotational offsets are made. The optimum offsets are then used to correct the input source positions which will be added as separate columns to input X-ray source catalogue.

### 3.1 Statistical method

The statistic for optimizing the match between optical and X-ray sources is:

$$L = \sum_{i=1}^{n_x} \sum_{j=1}^{n_o} \exp(-\frac{1}{2} (\frac{r_{ij}}{\sigma_{ij}})^2),$$
(1)



with  $r_{ij}$  the distance between an X-ray (i) and an optical source (j),  $\sigma_{ij}$  the associated error and  $n_x$  resp.  $n_o$  the number of X-ray sources and optical sources in the list. In the eposcorr task only those optical sources are considered which are within  $5\sigma$  of an X-ray source (for a given position offset).

In the following we will assume that the errors in the RA and DEC are equal and uncorrelated and follow a Gaussian distribution, we can then write  $\sigma_x = \sigma_y = \sigma^1$ . For the expectation value of L for a given X-ray source we get:

$$L = \frac{1}{2\pi\sigma^2} \int dx \int dy \exp(-\frac{1}{2}\frac{x^2 + y^2}{\sigma^2}) \exp(-\frac{1}{2}\frac{x^2 + y^2}{\sigma^2}) = \frac{1}{2\pi\sigma^2} \int dr \ 2\pi r \ \exp(-\frac{r^2}{\sigma^2}) = \frac{1}{2}.$$
 (2)

The associated variance in L is:

$$< L^{2} > - < L >^{2} = \int dr \ 2\pi r \ \exp(-\frac{1}{2}\frac{r^{2}}{\sigma^{2}}) \left(\exp(-\frac{1}{2}\frac{r^{2}}{\sigma^{2}})\right)^{2} - \left(\frac{1}{2}\right)^{2} = \frac{1}{3} - \frac{1}{4} = \frac{1}{12}$$
 (3)

Of course, in practice there will be chance coincidences. For chance coincidences the chance that an optical counter part will be within a distance r from the source is  $\pi r^2/\pi (5\sigma)^2$  (i.e. within an error circle of  $5\sigma$ ). This gives for the expected value L for a chance coincidence:

$$L = \int_0^{5\sigma} dr \frac{2\pi r}{\pi 25\sigma^2} \exp(-\frac{1}{2}\frac{r^2}{\sigma^2}) = \frac{2}{25} \left(1 - \exp(-\frac{25}{2})\right) \simeq \frac{2}{25}.$$
 (4)

And for the variance in L:

$$< L^{2} > - < L >^{2} = \int_{0}^{5\sigma} dr \frac{2\pi r}{\pi 25\sigma^{2}} \exp(-\frac{r^{2}}{\sigma^{2}}) - \left(\frac{2}{25}\right)^{2} = \frac{1}{25} \left(1 - \exp(-25)\right) - \left(\frac{2}{25}\right)^{2} \simeq \frac{1}{25} - \left(\frac{2}{25}\right)^{2} = \frac{21}{25^{2}}.$$
(5)

The number of chance coincidences can be estimated using poison statistics with a poison parameter of  $\mu = 25\pi\sigma^2\lambda$ , with  $\lambda$  the average number of optical sources per unit area. The expected number of sources is thus  $\sum_{i=1}^{n_x} \mu_i$  (where the subscript *i* denotes values for each X-ray source, thus allowing for fluctuations in the number of optical sources per area). The expected value for *L* is:

$$L = \sum_{i=1}^{n_x} \mu_i \int_0^{5\sigma_i} dr \; \frac{2\pi r}{\pi \; 25\sigma^2} \exp(-\frac{1}{2} \frac{r^2}{\sigma^2}) = \frac{2}{25} \sum_{i=1}^{n_x} \mu_i. \tag{6}$$

How many counterparts do we need to discriminate between chance coincidences or real counter parts? This question is not easy to answer, as **eposcorr** optimizes L and also for the number of counter parts. This means that Poissonian statistics may not be valid. To get at least an approximate answer, we equate:

$$(L_{exp} - 2\sigma_L)_{gaussian} = (L_{exp} + 2\sigma_L)_{poissonian},\tag{7}$$

or,

$$\frac{N}{2} - 2\sqrt{\frac{N}{12}} = \frac{2N}{25} + 2\sqrt{\frac{2N}{25^2}}.$$
(8)

The solution of this equation is N = 5.1. I therefore propose to use this number plus the number of degrees of freedom as the minimum threshold for accepting a result of **eposcorr**. This means that when offsets and in RA and DEC are corrected for the minimum number of optical counter parts should be 7, including a rotational correction this will be 8. This number will be contained in the keyword NMATCHES.

<sup>&</sup>lt;sup>1</sup>This is different from the definition used by the source detect codes there  $\sigma = \sqrt{\sigma_x^2 + \sigma_y^2}$ . This is corrected for in **eposcorr** 



### 3.2 The errors in the measured off-sets

At the moment we have no rigorous mathematical method to handle the statistical errors of the offsets found. For the moment we use the square root of the second order moment in L as a function of off-set divided by the number of optical counter parts.

### 3.3 Some spherical geometry

**eposcorr** calculates angular distances directly using spherical trigonometry. In particular the following is used to calculate the angular distance,  $\theta$ , between two sources (labeled 1 and 2).

$$\cos(\theta) = \sin(\delta_1)\sin(\delta_2) + \cos(\delta_1)\cos(\delta_2)\cos(\Delta\alpha),\tag{9}$$

where  $\delta$  refers to the declination of a source and  $\Delta \alpha = \alpha_1 - \alpha_2$ , the difference of the right ascension of the two sources.

### 4 Parameters

This section documents the parameters recognized by this task (if any).

1		0 7	( )/	
Parameter	Mand	Type	Default	Constraints
				-

 xrayset
 yes
 set

 File name for the fits binary table containing X-ray source positions and their errors.

opticalset	yes	set		
File name for the fits binary t	able contain	ning optical	source positions and their	errors.

findrotation	no	boolean	no	
Search for a rotational offset (	or not?			

Search for a rotational offset or not?

niter	no	integer	3		1-8	
Once a solution is found a new	iteration ca	n be made u	ising a smaller	grid size. T	This parameter	determines
the number of iterations.						

maxoffset	no	real	8.0	4.0-15.0		
Constraint on the maximum RA/DEC offset.						

maxrotation	no	real	1.0	0.5 - 4.0		
Constraint on the maximum rotational offset.						



maxdist	no	real	20.0	10.0–120.0
All optical sources with dis	tances > m	axdist will be	e removed from	n the source list, in order to speed up
the correlation.				
maxposnerr	no	real	20.0	1.0-120.0
Neglect X-ray sources with	positional	errors > max	posnerr in po	sition fitting in order to get a closer
match to the real positions	on the sky			
usemaxdist	no	boolean	yes	
Use maxdist to make a pre	selection of	t optical source	es?	
minbmagn	no	real	0.0	-2.0-30.0
Preselect the optical list on	basis of B	Magnitude. H	Iere the minim	um is set.
maxbmagn	no	real	26.0	-2.0-30.0
Preselect the optical list on	basis of B	Magnitude. H	Here the maxim	num is set.
usebmagn	no	boolean	no	
Use the B magnitude to ma	ake a presel	lection of optio	cal sources?	
hmag	no	string	Bmagn	
Column name of optical B	magnitudes	s (column in si	ingle precision)	)
I I I I I I I I I I I I I I I I I I I	.0		0 1	
•		1		
minrmagn Precedent the entired list on	no basis of P	real	0.0	-2.0-30.0
r reselect the optical list on	Dasis of h	magnitude. 1		tum is set.
maxrmagn	no	real	26.0	-2.0-30.0
Preselect the optical list on	basis of R	Magnitude. H	Here the maxim	num is set.

usermagnnobooleannoUse the R magnitude to make a preselection of optical sources?



makeimage	no	boolean	no			
yes: the grid containing likeli	hood values	will be writ	ten as a fits image file	<u>`</u>		
imaganama	no	flonomo	likelihood test fits	constraints		
the name of the image file cou	taining the	likelihood y		constraints		
the name of the image me con	itanning the	inkennood v	artes			
opticalra	no	string	CAT_RA			
Column name of optical catal	ogue positio	on RA (colu	mn in single or double pro	ecision)		
· · · · ·		· . •				
Opticaldec	no	string	CAT_DEC			
Column name of optical catal	ogue positio	on DEC (col	umn in single or double p	precision)		
opticalradecerr	no	string	CAT_RADEC_ERR			
Column name of optical catal	ogue positio	on error (col	umn in single or double p	recision)		
-	01	(	0 1	,		
opticaltableext	no	string	RAWRES			
Optical catalogue fits table ex	tension nan	ne				
wnowno	no	string	РΛ			
Column name of X-ray source	position R	Δ	IIA			
Column name of A ray source	position it.	11				
xraydec	no	string	DEC			
Column name of X-ray source	e position D	EC				
	1			1		
xrayradecerr	no	string	RADEC_ERR			
Column name of X-ray source	e position er	ror				
xravtableext	no	string	SRCLIST			
X-ray source list fits table ext	ension name	e				
		-				



			1			
raoffset	no	real	0.0			
RA offset (arcsec) to be used if calculateoffsets=no						
		1	1			
decoffset	no	real	0.0			
DEC offset (arcsec) to be use	d if calculate	eoffsets=no				
		-	1	1		
rotation	no	real	0.0			
rotation angle (degrees) to be	used if calc	ulateoffsets	=no			
	1					
withmatchtable	no	boolean	no			
write optional table of matche	ed objects					
matchset	no	string	matches.fits			
name of matched objects file						
rawxsyserr	no	real	1.5			
systematic error of input X-ra	y positions					
minxsyserr	no	real	0.2			
irreducible systematic error or	f X-ray posi	tions				
maxsig	no	real	5.0			
sigma cutoff for X-ray/optical	matches					
usemaxsig	no	boolean	yes			
use sigma cutoff limit						

# 5 Errors

This section documents warnings and errors generated by this task (if any). Note that warnings and errors can also be generated in the SAS infrastructure libraries, in which case they would not be documented here. Refer to the index of all errors and warnings available in the HTML version of the SAS documentation.



#### emptyList (error)

One of the source lists does not contain any data. (Can occur during processing of the data.)

#### emptySrcList (error)

The data set with the X-ray source list is empty. (Input error.)

#### emptyCatList (error)

The data set with the optical source list is empty. (Input error.)

#### invalidDec (warning)

Apparently this source is very close to the equatorial pole and the RA is not well defined *corrective action:* The value of RA\_CORR for a particular source will be set to 0.

#### noBmagnColumn (warning)

The optical source list set does not contain a column with B magnitudes *corrective action:* Ignore the B magnitudes, in case usebmagn was set to yes

#### noRmagnColumn (warning)

The optical source list set does not contain a column with R magnitudes *corrective action:* Ignore the R magnitudes, in case usermagn was set to yes

#### noRaDcPnt (warning)

The X-ray data set does not contain the RA\_PNT and/or DEC\_PNT keywords. As its values are used for the rotation, without these keywords no rotations can be found. *corrective action:* Do not optimize for a rotational offset

#### invalidLikelihood (warning)

The value for the statistic used to optimize the offsets is too low, so that the solution may not be reliable.

corrective action: The corrective action is up to the user

#### NoUnit (warning)

No RA unit; deg assumed corrective action: Assume RA values are in degrees

#### NoUnit (warning)

No DEC unit; deg assumed corrective action: Assume DEC values are in degrees

#### NoUnit (warning)

No error unit; arcsec assumed *corrective action:* Assume errors are in arcsec

### 6 Input Files

- 1. PPS product: list with right ascension (RA), declination (DEC). and position error (RA\_DEC\_ERR) of detected X-ray sources (default values of the column names are given in brackets)
- 2. Optical object catalogue used for cross-correlation, containing columns with right ascension (CAT\_RA), declination (CAT\_DEC), and position error (CAT\_RADEC\_ERR) of the catalogue objects (default values of the column names are given in brackets)



# 7 Output Files

From version 1.1 on the output routine tests if the columns RA\_CORR and DEC\_CORR are already present in the input/output file. Depending on the presence of these columns it will either add them or modify them. After the task has been run the following items will be present:

- 1. X-ray source list with two additional columns, being the corrected RA and DEC called RA\_CORR and DEC\_CORR.
- 2. The following keywords are added to the table: RAOFFSET, DEOFFSET, which indicate the offsets in RA and DEC used to correct the positions; RAOFFERR, DEOFFERR (the associated statistical errors) and LIK\_HOOD (containing the likelihood statistic) and NMATCHES. The keywords ROT\_CORR (rotational correction) and ROT\_ERR (error in rotation) are also added. The keyword LIK\_NULL contains the likelihood that can be expected from spurious matches only. It depends on the number of X-ray sources, the distribution of their positional errors, and the surface density of optical sources.
- 3. An optional image will be produced containing a map of likelihood values. This image can be used to check the uniqueness of the optimization routine.

## 8 Algorithm

```
subroutine eposcorr
   read x-ray and optical list
   call find_offset
   call correct_positions
   IF findrotation == TRUE THEN
      call find_all ! make a three dimensional search
   DO i=1, niter
      IF findrotation == TRUE THEN
         call find_rotation
      call find_offsets
    update the grid resolution
    ! for the last iteration a larger grid is used in order to get an error
    ! estimate
   END
   modify/write the x-ray list
end subroutine eposcorr
subroutine find_offset
   x_shift= y_shift =0
   LOOP over x_offset grid elements
```



LOOP over y\_offset grid elements

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```
call subroutine likelihood
           store likelihood in array
           IF likelihood > best likelihood THEN
             update best likelihood, x_shift=x_offset , y_shift=y_offset
       END LOOP
   END LOOP
   xm = ym = 0
    total_likelihood = 0
   LOOP over likelihood array elements (= corresponding x_offset, y_offset)
     IF( distance( x/y_offset , x/y_shift ) < 0.5* grid size ) THEN
       xm = xm + likelihood * (x_offset - x_shift)
       ym = ym + likelihood * (y_offset - y_shift)
        total_likelihood = total_likelihood + likelihood
     END IF
   END LOOP
    ! New best offsets:
   x_shift = xm/total_likelihood
   y_shift = ym/total_likelihood
end subroutine find_offset
subroutine likelihood
    set likelihood = 0
    set nmatches
                 = 0
   LOOP over elements X-ray list
       LOOP over elements optical list
            calculate the combined position error (sigma)
            calculate the distance (d) between the optical and X-ray source
                      for given x and y offsets
            IF x-ray source within 5 sigma of optical source THEN
             nmatches = nmatches + 1
              likelihood = likelihood + exp{ -0.5 * (d/sigma)^2 }
           END IF
       END LOOP
   END LOOP
end subroutine likelihood
```

### 9 Comments

• At the moment the critical value for the likelihood is set to 0.3, which is somewhat arbitrary.



# 10 Future developments

- More research will be done on the expectation values for the likelihood statistic. This will include several possible situations (purely Poissonian coincidences, real correlations and mixtures). This will help distinguishing reliable corrections from unreliable corrections. This implies that some additional keywords may be added in future which give information about the correlation.
- Some research could be done to other methods for determining offset. One can think of Fast Fourier Transforms for fast correlations, or a method based on triangle patterns.

## References